

COURS RDFIA deep Image

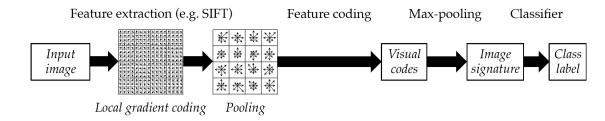
Matthieu Cord Sorbonne University

Course Outline

- 1. Computer Vision and ML basics: Visual (local) feature detection and description, Bag of Word Image representation, Linear classification (SVM)
- 2. Introduction to Neural Networks (NNs)
- 3. Machine Learning basics (2): Risk, Classification, Datasets, benchmarks and evaluation
- 4. Neural Nets for Image Classification
- **5. Vision Transformers**

Context: Image classification **Before/After** ImageNet (2009)

The 2000s: *BoWs image modeling + SVMs* for Visual Classification



The star: ConvNet / ImageNet1k

Coding

Pooling

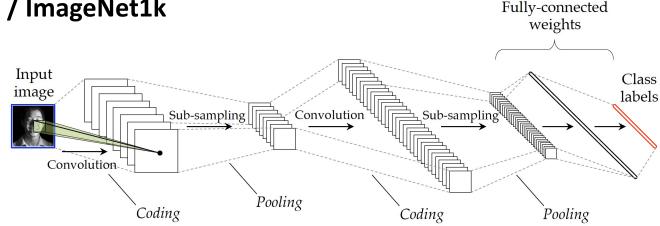
Coding

Pooling

Context: Image classification After ImageNet (2009)

The 2010s: Large deep neural nets for Visual Classification

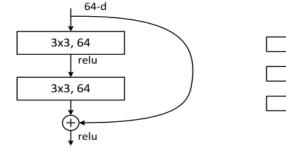
The star: ConvNet / ImageNet1k



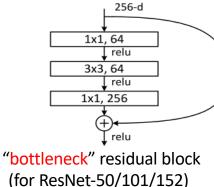
AlexNet 2012

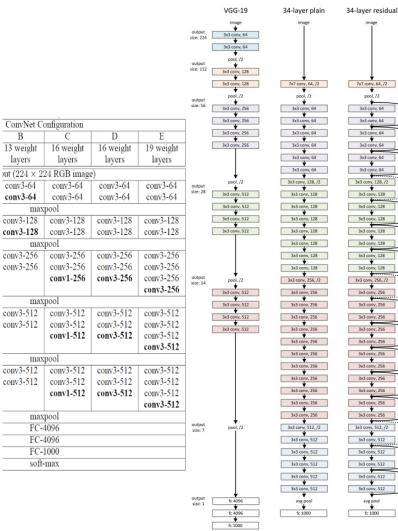
- Same model as LeCun'98 but:
 - Bigger model (8 layers)
 - More data $(10^6 \text{ vs } 10^3 \text{ images})$
 - GPU implementation (50x speedup over CPU)
 - Better regularization (DropOut)

Post-2012 revolution: **ResNet Architecture**



A naïve residual block





nonl. /2

3x3 conv. 64

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3x3 conv, 64

3x3 conv, 64

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3x3 conv, 64

3x3 conv, 64

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3x3 conv, 64

3x3 conv, 128, /2

3x3 conv, 128

3x3 conv, 128

3x3 conv, 128

3x3 conv, 128

¥ 3x3 conv, 128

3x3 conv, 128

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3x3 conv, 128

3x3 conv, 256

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3x3 conv, 256

3x3 conv, 256

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3x3 conv, 256

3x3 conv, 512

3x3 conv, 512

3x3 conv, 512

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3x3 conv, 512

3x3 conv, 512

avg pool

fc 1000

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Context: Beyond ImageNet?

The 2000s: *BoWs image modeling + SVMs* for Visual Classification The 2010s: *Large* deep neural nets for Visual Classification

What is expected for the 2020s?

"Attention is all you need": **Transformers** for Vision !?

And datasets? Internet...

[Vaswani et al., Attention is all you need, NeurIPS 2017]

Outline

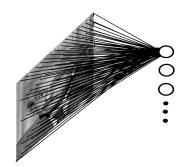
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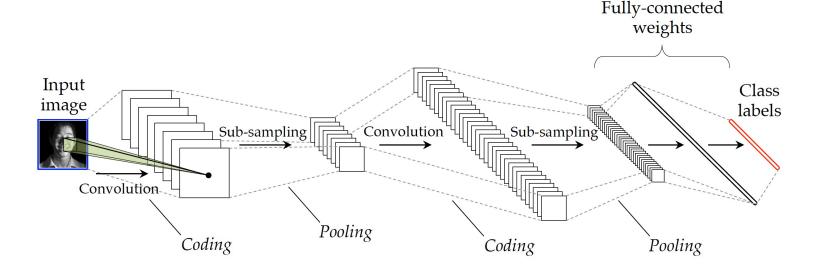
NLP: Attention is all you need

Attention process in ConvNets

In ConvNets, what information is shared between pixels (or features) in one block? => 2D spatial locality (typically 3x3) => attention is done locally

Rq: less local after many layers

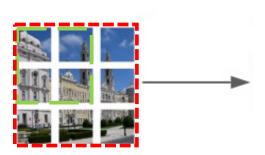


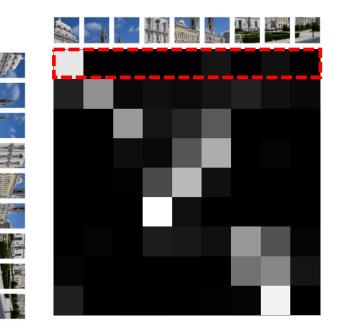


Global (Self) attention

How to build a deep architecture with local global attention inside? Meaning that one patch may interact with all others!

=> Different than convNet!

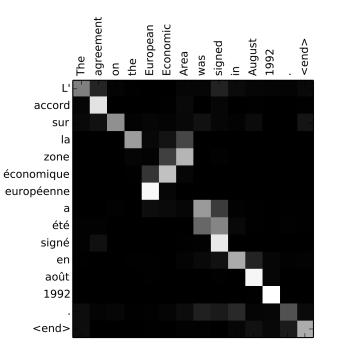




Let's see what they do in Natural Language Processing (NLP):

Attention between words in Machine translation process:

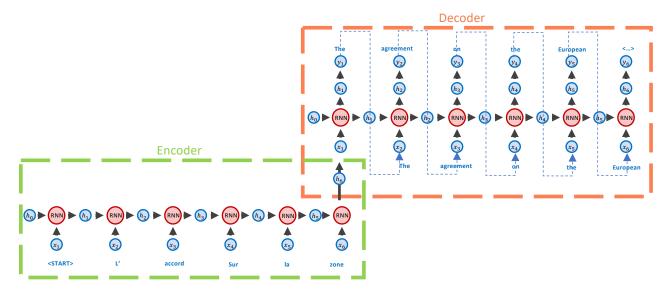
- 1. Computing of weights
- 2. Use them to compute new features



Basic language translation models: Encoder/Decoder

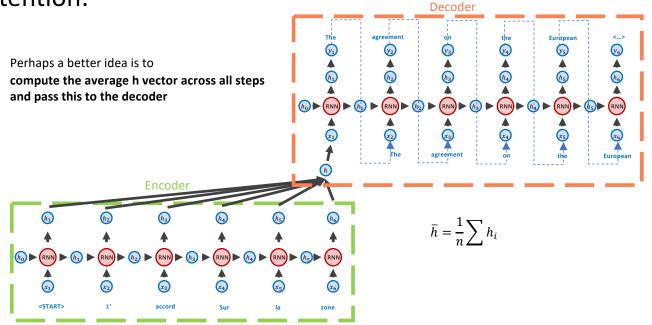
Ex.: Seq2Seq -- RNNs2RNNs

Cross-attention for language translation in at the end of Encoder



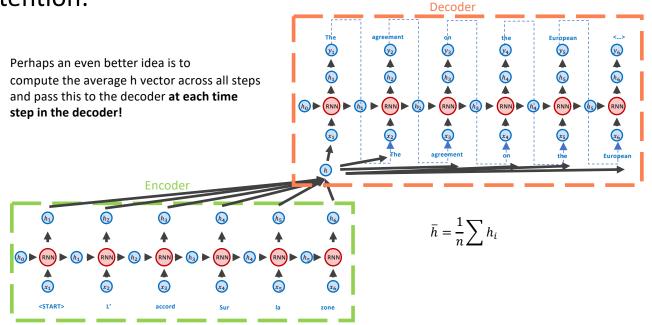
Basic language translation models: Encoder/Decoder

Cross-attention:



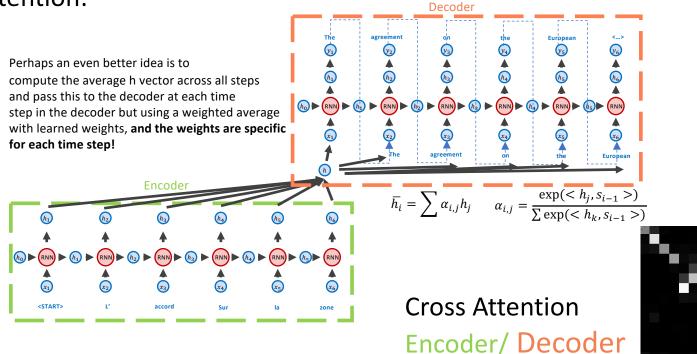
Basic language translation models: Encoder/Decoder

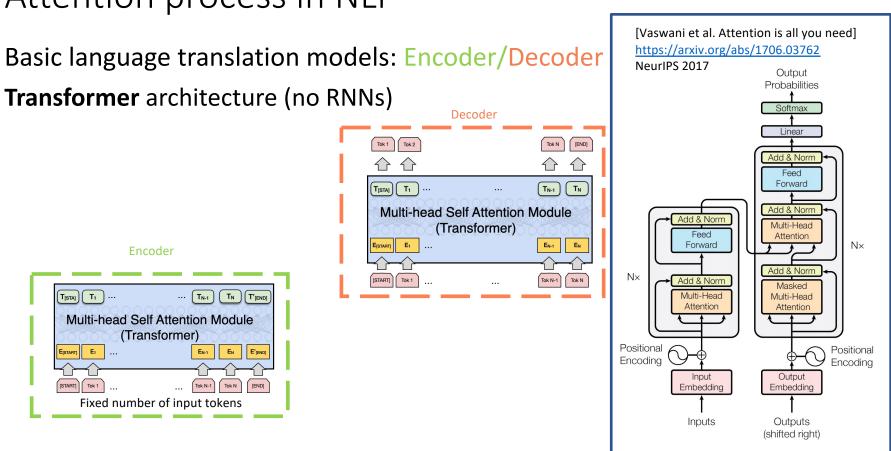
Cross-attention:

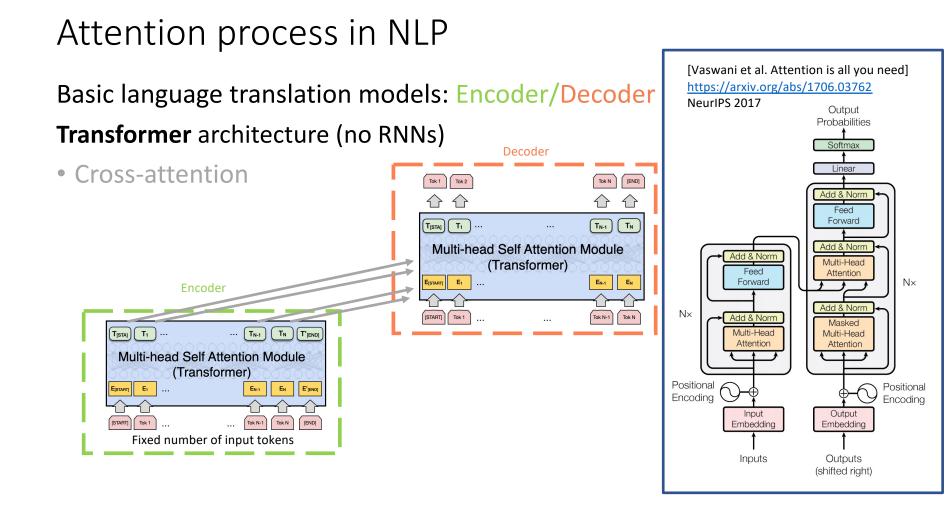


Basic language translation models: Encoder/Decoder

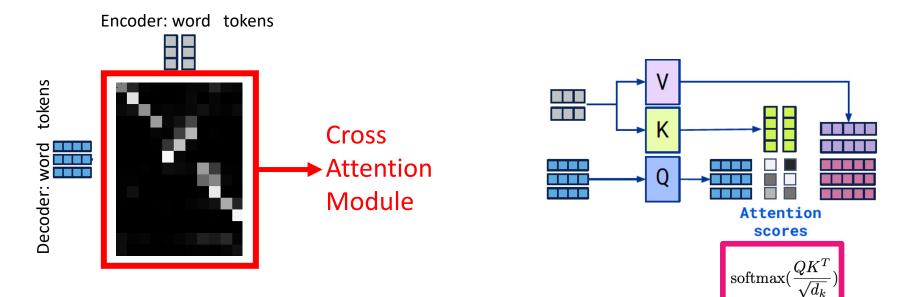
Cross-attention:







Attention process in NLP [Vaswani et al. Attention is all you need] Basic language translation models: Encoder/Decoder https://arxiv.org/abs/1706.03762 NeurIPS 2017 Output Probabilities **Transformer** architecture (no RNNs) Softmax Decoder Cross-attention Linear Tok 2 [END] Tok 1 Tok N Add & Norm Self-attention Feed Forward T_[STA] T₁ ... TN T_{N-1} Multi-head Self Attention Module Add & Norm Add & Norm Multi-Head (Transformer) Feed Attention N× Forward E[START] E1 E_{N-1} Encoder Add & Norm N× [START] Tok 1 Tok N-1 Add & Norm Tok N Masked TN T'[END] Multi-Head (T_{N-1} Multi-Head Attention Attention Multi-head Self Attention Module (Transformer) Positional Positional EN E'IENDI Encoding Encoding Input Output Tok N [END] Embedding Embedding Fixed number of input tokens Inputs Outputs (shifted right)



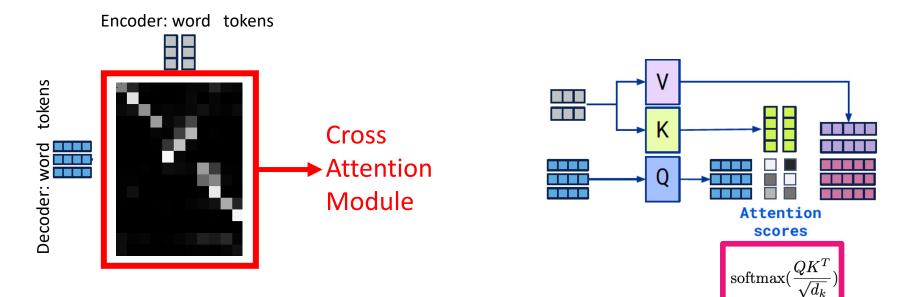
$$\operatorname{Attention}(Q, K, V) = \operatorname{softmax}(\frac{QK^T}{\sqrt{d_k}})V$$

Outline

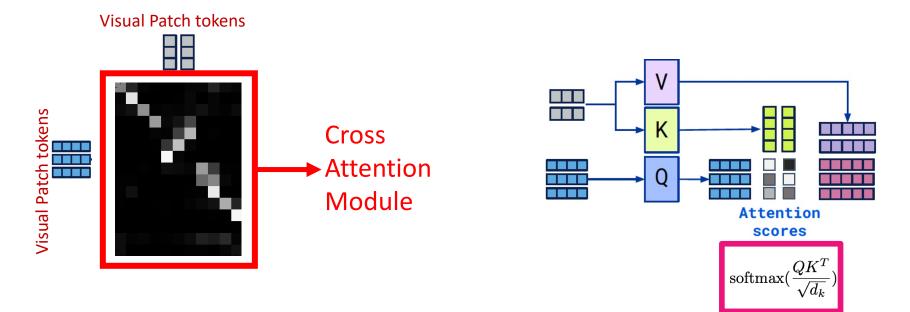
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NLP: Attention is all you need

Transformer for image classification



$$\operatorname{Attention}(Q, K, V) = \operatorname{softmax}(\frac{QK^T}{\sqrt{d_k}})V$$



$$\operatorname{Attention}(Q, K, V) = \operatorname{softmax}(\frac{QK^T}{\sqrt{d_k}})V$$

Very similar except that Visual token is definitively less natural than word for NLP

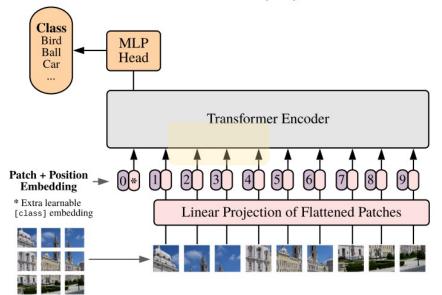
Is it possible to mimic this attentionbased architecture for vision processing?

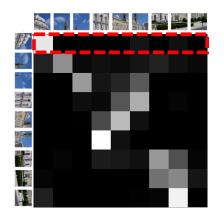
Yes! **ViT** (Vision image Transformers) architecture

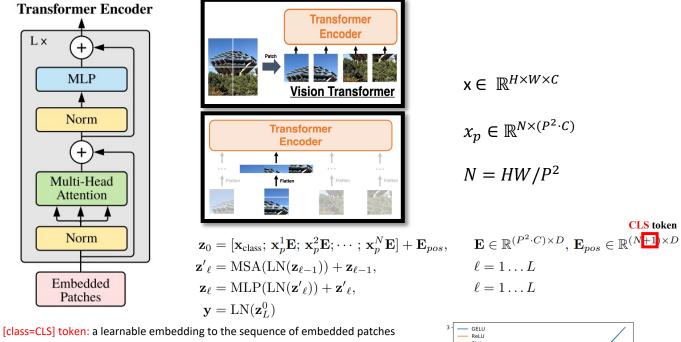


AN IMAGE IS WORTH 16x16 WORDS: TRANSFORMERS FOR IMAGE RECOGNITION AT SCALE

Alexey Dosovitskiy^{*,†}, Lucas Beyer^{*}, Alexander Kolesnikov^{*}, Dirk Weissenborn^{*}, Xiaohua Zhai^{*}, Thomas Unterthiner, Mostafa Dehghani, Matthias Minderer, Georg Heigold, Sylvain Gelly, Jakob Uszkoreit, Neil Houlsby^{*,†} ^{*}equal technical contribution, [†]equal advising Google Research, Brain Team {adosovitskiy, neilhoulsby}@google.com





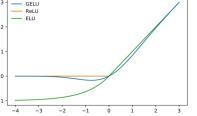


Layernorm (LN) before every block, and residual connections after every block

MSA: Multi Head Self Attention

MLP: two layers with a GELU non-linearity

Hybrid Architecture : Raw image patches --> Feature map of a CNN



Experiments with ViT (and variants DeiT, CaiT) transformers for image classification

State-of-the-art performance on ImageNet1k classification!

From ViT paper, **many tricks/discussions to simplify learning** in DeiT, CaiT, ...

